# A note on the existence of global solutions for reaction-diffusion equations with almost-monotonic nonlinearities 

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## 1 Introduction

Let us consider the following problem

$$
\left\{\begin{align*}
u_{t}-\Delta u & =f(x, u) & & \text { in } \Omega  \tag{1.1}\\
u & =0 & & \text { on } \Gamma \\
u(0) & =u_{0} & & \text { in } \Omega
\end{align*}\right.
$$

in a bounded domain $\Omega \subset \mathbb{R}^{N}, N \geq 1$, with $f$ of the form

$$
\begin{equation*}
f(x, u)=g(x)+m(x) u+f_{0}(x, u), \quad x \in \Omega, u \in \mathbb{R} \tag{1.2}
\end{equation*}
$$

where

$$
\begin{equation*}
g \in L^{q_{0}}(\Omega), \text { with } N / 2<q_{0}<\infty, \quad m \in L^{r_{0}}(\Omega) \text { with } N / 2<r_{0} \leq \infty \tag{1.3}
\end{equation*}
$$

and $f_{0}$ is a Carathéodory function, locally Lipschitz in the second variable in a $L^{q_{0}}(\Omega)$ form with respect to $x \in \Omega$, i.e, such that for $|u| \leq R$ and $|v| \leq R$ we have

$$
\left|f_{0}(x, u)-f_{0}(x, v)\right| \leq L_{0}(x, R)|u-v|
$$

with $0 \leq L_{0}(\cdot, R) \in L^{q_{0}}(\Omega)$ for each $R>0$, and with $f_{0}(\cdot, 0)=\partial_{u} f_{0}(\cdot, 0)=0$.
Our goal here is to prove global existence and uniqueness of solutions for initial data $u_{0} \in L^{q}(\Omega)$ for any $1 \leq q<\infty$ under the only additional assumption that $f_{0}(x, u)$ is almost monotonic, i.e, to satisfy the following condition

$$
\begin{equation*}
\partial_{u} f_{0}(x, u) \leq L(x), \quad \text { for all } \quad x \in \Omega, u \in \mathbb{R} \tag{1.4}
\end{equation*}
$$

for some $L \in L^{\sigma_{0}}(\Omega), \sigma_{0}>N / 2$. Note that this implies

$$
\begin{equation*}
u f(x, u) \leq C(x) u^{2}+D(x)|u|, \quad x \in \Omega, u \in \mathbb{R} \tag{1.5}
\end{equation*}
$$

for $C=m+L \in L^{\sigma}(\Omega), \sigma=\min \left\{r_{0}, \sigma_{0}\right\}>N / 2$ and $0 \leq D=|g| \in L^{q_{0}}(\Omega)$.

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## 2 Preliminary results

Notice that, the Nemytskii operator associated to $F(x, u)=g(x)+f_{0}(x, u)$ maps bounded sets of $L^{\infty}(\Omega)$ into bounded sets of $L^{q_{0}}(\Omega)$ and so we have the existence of local solutions of problem (1.1) for smooth initial data. Namely, we have (see [6])
Theorem 2.1 Assume that $f$ is as in (1.2)-(1.3). If $\alpha<1$ is such that $2 \alpha-\frac{N}{q_{0}}>0$, then for any initial data $u_{0} \in H^{2 \alpha, q_{0}}(\Omega) \cap H_{0}^{1, q_{0}}(\Omega)$ there exists a unique local solution of (1.1) with initial data $u_{0}$, with $u\left(\cdot ; u_{0}\right) \in C\left([0, \tau) ; H^{2 \alpha, q_{0}}(\Omega) \cap H_{0}^{1, q_{0}}(\Omega)\right) \cap C\left((0, \tau) ; H^{2, q_{0}}(\Omega)\right)$ and $u_{t} \in C\left((0, \tau) ; H^{2 \gamma, q_{0}}(\Omega) \cap H_{0}^{1, q_{0}}(\Omega)\right)$ for any $\gamma<1$, for some $\tau$ depending on $u_{0}$.

The solution satisfies the Variation of Constant Formula,

$$
u\left(t ; u_{0}\right)=S_{m}(t) u_{0}+\int_{0}^{t} S_{m}(t-s)\left(g+f_{0}\left(u\left(s ; u_{0}\right)\right)\right) \mathrm{d} s
$$

where $S_{m}$ denotes the semigroup generated by $\Delta+m(x) I$ with Dirichlet boundary conditions.

Note that since $q_{0}>N / 2, H^{2 \alpha, q_{0}}(\Omega) \cap H_{0}^{1, q_{0}}(\Omega) \subset C_{0}^{\eta}(\bar{\Omega})$ for any $0 \leq \eta<2-N / q_{0}$. In particular the solution satisfies $u \in C([0, \infty) \times \bar{\Omega})$. Also, if $g$ and $L_{0}(\cdot, R)$, for each $R$, are a bounded functions, then the above holds for any $q_{0}>N / 2$.

It is known that condition (1.5) ensures the global existence of the local solutions in Theorem 2.1 (see [2] and [10]). Namely, we have
Theorem 2.2 Assume that $f$ is as in (1.2)-(1.3) and satisfies (1.5), that is

$$
u f(x, u) \leq C(x) u^{2}+D(x)|u|, \quad x \in \Omega, u \in \mathbb{R}
$$

for some $C \in L^{\sigma}(\Omega)$ and $0 \leq D \in L^{\rho}(\Omega)$ with $\sigma, \rho>N / 2$.
Then for the solutions in Theorem 2.1 one has $\tau=\infty$.

## 3 Existence in $L^{q}(\Omega), 1 \leq q<\infty$

The goal of the section is to prove main result in this work. Namely, the existence of a unique solution of problem (1.1) starting at $u_{0} \in L^{q}(\Omega)$ for any $1 \leq q<\infty$.
Theorem 3.1 Let $1 \leq q<\infty$. Suppose that $f$ is as in (1.2)-(1.3) and $f_{0}$ satisfies (1.4) with $L \in L^{\sigma_{0}}(\Omega), \sigma_{0}>N / 2$. Then, for any $u_{0} \in L^{q}(\Omega)$, there exists a solution of (1.1) defined for all $t \geq 0, u$, such that

$$
u \in C\left([0, \infty) ; L^{q}(\Omega)\right) \cap C\left((0, \infty) ; H^{2, q_{0}}(\Omega) \cap H_{0}^{1, q_{0}}(\Omega)\right), \quad u(0)=u_{0}
$$

and satisfies

$$
\begin{equation*}
u(t)=S_{m}(t) u_{0}+\int_{0}^{t} S_{m}(t-s)\left(g+f_{0}(\cdot, u(s))\right) \mathrm{d} s \tag{3.1}
\end{equation*}
$$

where $S_{m}$ denotes the semigroup generated by $\Delta+m(x) I$ with Dirichlet boundary conditions.

Moreover, for each $T>0$ there exists $c(T)$ such that

$$
\begin{equation*}
|u(t, x)| \leq c(T)\left(1+t^{-\frac{N}{2 q}}\left\|u_{0}\right\|_{L^{q}(\Omega)}\right), \quad 0<t \leq T \quad \text { for all } x \in \bar{\Omega} \tag{3.2}
\end{equation*}
$$

Proof. We proceed in several steps. In the first step, fixed $1 \leq q<\infty$, we construct a Cauchy sequence of approximating solutions. Then, we obtain a uniform $L^{\infty}(\Omega)$ bound for the approximating sequence. In a third step, we show that the limit of the approximating solutions is a solution of the limit problem (notice that such limit exists since the approximating solutions forms a Cauchy sequence). Finally, we show how to obtain more regularity of the solution constructed in the previous steps.

Without loss of generality we can assume that $L$ in (1.4) is non-negative.
Step 1. Approximate the initial data. Let $\alpha<1$ such that $2 \alpha-\frac{N}{q_{0}}>0$. Then, by Theorem [2.1, the problem (1.1) is well-posed in $H^{2 \alpha, q_{0}}(\Omega) \cap H_{0}^{1, q_{0}}(\Omega)$. Also, since $f$ satisfies (1.5), the solutions are globally defined for $t>0$, see Theorem 2.2 and (1.5).

Hence, for any $1 \leq q<\infty$ and $u_{0} \in L^{q}(\Omega)$, we can take smooth enough initial data $u_{0}^{n} \in H^{2 \alpha, q_{0}}(\Omega) \cap H_{0}^{1, q_{0}}(\Omega)$ such that $u_{0}^{n} \rightarrow u_{0}$ in $L^{q}(\Omega)$ as $n \rightarrow \infty$ and consider the solutions of (1.1) starting at $u_{0}^{n}$. We define $u_{n}(t)=u\left(t ; u_{0}^{n}\right)$.

Let $v_{n, k}(t)=u_{n}(t)-u_{k}(t)$. Subtracting equations for $u_{n}$ and $u_{k}$, we have

$$
\left\{\begin{aligned}
\partial_{t} v_{n, k}(t)-\Delta v_{n, k}(t) & =m(x) v_{n, k}(t)+f_{0}\left(x, u_{n}(t)\right)-f_{0}\left(x, u_{k}(t)\right) & & \text { in } \Omega \\
v_{n, k} & =0 & & \text { on } \Gamma \\
v_{n, k}(0) & =u_{n}^{0}-u_{k}^{0} & & \text { in } \Omega .
\end{aligned}\right.
$$

Observe that for fixed $n, k$, we have for almost all $x \in \Omega, t \in[0, T]$ and some $0<$ $\theta(t, x)<1$

$$
\begin{aligned}
f_{0}\left(x, u_{n}(t, x)\right)-f_{0}\left(x, u_{k}(t, x)\right) & =\partial_{u} f_{0}\left(x, \theta(t, x) u_{n}(t, x)+(1-\theta(t, x)) u_{k}(t, x)\right) v_{n, k}(t, x) \\
& =C_{n, k}(t, x) v_{n, k}(t, x)
\end{aligned}
$$

for some function $C_{n, k}(t, x)$. Notice that $C_{n, k} \in L^{\infty}\left((0, T) ; L^{q_{0}}(\Omega)\right)$ since $u_{n}$ and $u_{k}$ are smooth, $f_{0}$ is locally Lipschitz in the second variable in an $L^{q_{0}}(\Omega)$ manner. Also, from (1.4) we have $C_{n, k}(x, t) \leq L(x)$ for all $t \geq 0$ and $x \in \Omega$.

Now, consider the linear problem

$$
\left\{\begin{align*}
z_{t}-\Delta z & =\left(m(x)+C_{n, k}(t, x)\right) z & & \text { in } \Omega  \tag{3.3}\\
z & =0 & & \text { on } \Gamma \\
z(0) & =z_{0} & & \text { in } \Omega
\end{align*}\right.
$$

with $z_{0}$ smooth and denote by $z\left(t, 0 ; z_{0}\right)$ the solution whose existence follows from [8] or [4]). Such solutions satisfy by comparison $z\left(t, 0 ;-\left|z_{0}\right|\right) \leq z\left(t, 0 ; z_{0}\right) \leq z\left(t, 0 ;\left|z_{0}\right|\right)$, i.e,

$$
\left|z\left(t, 0 ; z_{0}\right)\right| \leq z\left(t, 0 ;\left|z_{0}\right|\right)
$$

and the latter is a nonnegative solution of (3.3).
But for nonnegative initial data, $z_{0} \geq 0$, since $C_{n, k}(x, t) \leq L(x)$ for all $t \geq 0$ and $x \in \Omega$, we can compare $z\left(t, 0 ; z_{0}\right) \geq 0$ with the solutions of

$$
\left\{\begin{aligned}
w_{t}-\Delta w & =(m(x)+L(x)) w & & \text { in } \Omega \\
w & =0 & & \text { on } \Gamma \\
w(0) & =z_{0} & & \text { in } \Omega
\end{aligned}\right.
$$

to obtain $0 \leq z\left(t, 0 ; z_{0}\right) \leq w\left(t ; z_{0}\right)$.
Hence, we obtain that for any smooth initial data $z_{0}$ in (3.3) we have

$$
\left|z\left(t, 0 ; z_{0}\right)\right| \leq w\left(t ;\left|z_{0}\right|\right) \quad \text { for } t \geq 0
$$

In particular,

$$
\left\|z\left(t, 0 ; z_{0}\right)\right\|_{L^{q}(\Omega)} \leq\left\|w\left(t ;\left|z_{0}\right|\right)\right\|_{L^{q}(\Omega)} \leq c \mathrm{e}^{-\lambda t}\left\|z_{0}\right\|_{L^{q}(\Omega)}
$$

where $\lambda$ is the first eigenvalue of $-\Delta-(m(x)+L(x)) I$ on $\Omega$ with Dirichlet boundary conditions.

Now, $v_{n, k}$ is a solution of (3.3) and so

$$
\left\|v_{n, k}(t)\right\|_{L^{q}(\Omega)} \leq c \mathrm{e}^{-\lambda t}\left\|v_{n, k}(0)\right\|_{L^{q}(\Omega)}
$$

for all $t \geq 0$. In particular, given $T>0$, we have that for any $0 \leq t \leq T$,

$$
\left\|v_{n, k}(t)\right\|_{L^{q}(\Omega)} \leq c(T)\left\|v_{n, k}(0)\right\|_{L^{q}(\Omega)} \rightarrow 0 \quad \text { as } \quad n, k \rightarrow \infty
$$

and so, $u_{n}$ is a Cauchy sequence in $C\left([0, T] ; L^{q}(\Omega)\right)$.
Hence, there exists $u \in C\left([0, \infty) ; L^{q}(\Omega)\right)$ such that for any $T>0$,

$$
\begin{equation*}
\sup _{t \in[0, T]}\left\|u_{n}(t)-u(t)\right\|_{L^{q}(\Omega)} \leq c(T)\left\|u_{n}^{0}-u_{0}\right\|_{L^{q}(\Omega)} \rightarrow 0 \quad \text { as } \quad n \rightarrow \infty \tag{3.4}
\end{equation*}
$$

i.e, for any $T>0$,

$$
u_{n} \rightarrow u \quad \text { in } C\left([0, T] ; L^{q}(\Omega)\right) .
$$

In particular, passing to a subsequence if needed, $u_{n}(t, x) \rightarrow u(t, x)$ as $n \rightarrow \infty$ a.e. for $(t, x) \in[0, T] \times \Omega$.

Also it is easy to see that $u$ does not depend on the sequence of initial data, but only on $u_{0} \in L^{q}(\Omega)$.
Step 2. $L^{\infty}$-bound for the approximating sequence. Let us show now that the sequence $u_{n}(t)$ is uniformly bounded in $L^{\infty}(\Omega)$ with respect to $n$, for $0<\varepsilon \leq t \leq T$.

For this, since $f$ satisfies (1.5), we will use the auxiliary problem

$$
\left\{\begin{array}{rlll}
U_{t}-\Delta U & =C(x) U+D(x) & \text { in } \Omega  \tag{3.5}\\
U & =0 & \text { on } \Gamma \\
U(0) & & \text { given in } L^{q}(\Omega) &
\end{array}\right.
$$

with $C=m+L \in L^{\sigma}(\Omega), \sigma=\min \left\{r_{0}, \sigma_{0}\right\}>N / 2$ and $0 \leq D=|g| \in L^{q_{0}}(\Omega), q_{0}>N / 2$.
Denote by $U^{n}(t, x)$ the solution of (3.5) with initial data $\left|u_{0}^{n}\right|$ and by $U(t, x)$ the solution of (3.5) with initial data $\left|u_{0}\right|$.

Now, using the variation of constants formula in (3.5) we have

$$
U^{n}(t)=\Phi(t)+U_{h}^{n}(t), \quad U(t)=\Phi(t)+U_{h}(t)
$$

where $U_{h}^{n}(t), U_{h}(t)$ are the solutions of the homogeneous problem

$$
\left\{\begin{array}{rlr}
V_{t}-\Delta V & =C(x) V & \text { in } \Omega \\
V & =0 & \text { on } \Gamma \\
V(0) & & \text { given in } L^{q}(\Omega)
\end{array}\right.
$$

resulting from taking $D \equiv 0$ in (3.5) and initial data $\left|u_{0}^{n}\right|$ and $\left|u_{0}\right|$ respectively, and $\Phi(t)$ is the unique solution of problem (3.5) with $U(0)=0$ (which does not depend on $u_{0}^{n}$ or $u_{0}$ ), that is,

$$
\left\{\begin{aligned}
W_{t}-\Delta W & =C(x) W+D(x) & & \text { in } \Omega \\
W & =0 & & \text { on } \Gamma \\
W(0) & =0 & & \text { in } \Omega .
\end{aligned}\right.
$$

In other words $U_{h}^{n}(t)=S_{C}(t)\left|u_{0}^{n}\right|, U_{h}(t)=S_{C}(t)\left|u_{0}\right|$ and $\Phi(t)=\int_{0}^{t} S_{C}(t-s) D \mathrm{~d} s$ where $S_{C}$ denotes the semigroup generated by $\Delta+C(x) I$ with Dirichlet boundary conditions. Hence standard estimates implies that, for any $T>0$,

$$
\begin{array}{cc}
\left\|U^{n}(t)\right\|_{L^{\infty}(\Omega)} \leq c(T)\left(1+t^{-\frac{N}{2 q}}\left\|u_{0}^{n}\right\|_{L^{q}(\Omega)}\right), & 0<t \leq T \\
\left\|U^{n}(t)\right\|_{L^{q}(\Omega)} \leq c(T)\left(1+\left\|u_{0}^{n}\right\|_{L^{q}(\Omega)}\right), & 0 \leq t \leq T
\end{array}
$$

and

$$
\begin{aligned}
\left\|U^{n}(t)-U(t)\right\|_{L^{\infty}(\Omega)} & =\left\|U_{h}^{n}(t)-U_{h}(t)\right\|_{L^{\infty}(\Omega)}=\left\|S_{C}(t)\left(\left|u_{0}^{n}\right|-\left|u_{0}\right|\right)\right\|_{L^{\infty}(\Omega)} \\
& \leq c(T) t^{-\frac{N}{2 q}}\left\|\left|u_{0}^{n}\right|-\left|u_{0}\right|\right\|_{L^{q}(\Omega)} \rightarrow 0 \quad \text { as } \quad n \rightarrow \infty
\end{aligned}
$$

for $0<t \leq T$, and for $0 \leq t \leq T$

$$
\left\|U^{n}(t)-U(t)\right\|_{L^{q}(\Omega)} \leq c(T)\left\|\left|u_{0}^{n}\right|-\left|u_{0}\right|\right\|_{L^{q}(\Omega)} \rightarrow 0 \quad \text { as } \quad n \rightarrow \infty
$$

Therefore, for any $0<\varepsilon<T<\infty$,

$$
U^{n} \rightarrow U \quad \text { in } L^{\infty}([\varepsilon, T] \times \Omega) \cap C\left([0, T] ; L^{q}(\Omega)\right)
$$

Observe now that, since $f$ satisfies (1.5), $U^{n}(t, x)$ is a supersolution of problem (1.1) and $-U^{n}(t, x)$ is a subsolution. Thus,

$$
\begin{equation*}
\left|u_{n}(t, x)\right| \leq U^{n}(t, x) \leq c(T)\left(1+t^{-\frac{N}{2 q}}\left\|u_{0}^{n}\right\|_{L^{q}(\Omega)}\right), \quad 0<t \leq T, \quad \text { a.e. in } \Omega \tag{3.6}
\end{equation*}
$$

and so

$$
\left\|u_{n}(t)\right\|_{L^{\infty}(\Omega)} \leq c\left(\varepsilon, T,\left\|u_{0}^{n}\right\|_{L^{q}(\Omega)}\right), \quad \varepsilon \leq t \leq T
$$

Now, since $u_{0}^{n} \rightarrow u_{0}$ in $L^{q}(\Omega)$ as $n \rightarrow \infty$ and the convergences $U^{n}(t, x) \rightarrow U(t, x)$ and $u_{n}(t, x) \rightarrow v(t, x)$ obtained above (see (3.4)) we get

$$
\begin{equation*}
|u(t, x)| \leq U(t, x) \leq c(T)\left(1+t^{-\frac{N}{2 q}}\left\|u_{0}\right\|_{L^{q}(\Omega)}\right), \quad 0<t \leq T, \quad \text { for a.e. } x \in \Omega \tag{3.7}
\end{equation*}
$$

Now observe that the bounds above, the regularity of $u_{n}$ in Theorem 2.1 and (3.4) imply that for any $0<\varepsilon<T<\infty$ and $1 \leq s<\infty$,

$$
\begin{equation*}
\sup _{t \in[\varepsilon, T]}\left\|u_{n}(t)-u(t)\right\|_{L^{s}(\Omega)} \rightarrow 0 \quad \text { as } \quad n \rightarrow \infty \tag{3.8}
\end{equation*}
$$

i.e, for any $T>0$ and $1 \leq s<\infty$,

$$
u_{n} \rightarrow u \quad \text { in } C\left([\varepsilon, T] ; L^{s}(\Omega)\right) .
$$

In particular $u \in C\left((0, \infty) ; L^{s}(\Omega)\right)$ for any $1 \leq s<\infty$.
Step 3. The limit is a solution of (1.1). First, assume $0<\varepsilon<t<T$. Then for any $\phi \in H^{2, q_{0}^{\prime}}(\Omega) \cap H_{0}^{1, q_{0}^{\prime}}(\Omega)$, where $q_{0}^{\prime}$ is the conjugate of $q_{0}$, i.e, $\frac{1}{q_{0}}+\frac{1}{q_{0}^{\prime}}=1$ (as usual, for $q_{0}=1$ we take $q_{0}^{\prime}=\infty$ ), we have from (1.1) and the regularity if $u_{n}$ in Theorem 2.1,

$$
\frac{\mathrm{d}}{\mathrm{~d} t} \int_{\Omega} u_{n} \phi+\int_{\Omega} u_{n}(-\Delta \phi)=\int_{\Omega} f\left(\cdot, u_{n}\right) \phi=\int_{\Omega} g \phi+\int_{\Omega} m(x) u_{n} \phi+\int_{\Omega} f_{0}\left(x, u_{n}\right) \phi
$$

Now, using the uniform bounds in (3.6), (3.7) and the convergence in (3.8), and the fact that $f_{0}$ is locally Lipchitz in its second variable in an $L^{q_{0}}(\Omega)$ manner, we have that for $1 \leq s \leq q_{0}$,

$$
f_{0}\left(\cdot, u_{n}\right) \rightarrow f_{0}(\cdot, u) \quad \text { in } \quad C\left([\varepsilon, T] ; L^{s}(\Omega)\right) .
$$

Hence, letting $n \rightarrow \infty$, we get

$$
\frac{\mathrm{d}}{\mathrm{~d} t} \int_{\Omega} u \phi+\int_{\Omega} u(-\Delta \phi)=\int_{\Omega} f(\cdot, u) \phi=\int_{\Omega} g \phi+\int_{\Omega} m(x) u \phi+\int_{\Omega} f_{0}(x, u) \phi .
$$

Notice that from [3], this implies

$$
\begin{equation*}
u(t)=S_{m}(t-\varepsilon) u(\varepsilon)+\int_{\varepsilon}^{t} S_{m}(t-s) h(s) \mathrm{d} s \tag{3.9}
\end{equation*}
$$

where $S_{m}(t)$ denotes the strongly continuous analytic semigroup generated by $\Delta+m(x) I$ with homogeneous Dirichlet boundary conditions, and $h(\cdot)=g+f_{0}(\cdot, u(\cdot)) \in L^{\infty}\left([\varepsilon, T] ; L^{q_{0}}(\Omega)\right)$.

The smoothing effect of the semigroup gives that

$$
\int_{\varepsilon}^{t} S_{m}(t-s) h(s) \mathrm{d} s \in C\left([\varepsilon, T] ; H^{2 \gamma, q_{0}}(\Omega) \cap H_{0}^{1, q_{0}}(\Omega)\right), \text { for any } \gamma<1
$$

while the continuity of the linear semigroup $S_{m}(t)$ at 0 and $u(\varepsilon) \rightarrow u_{0}$ in $L^{q}(\Omega)$ as $\varepsilon \rightarrow 0$, give, taking $\varepsilon \rightarrow 0$ in (3.9),

$$
\int_{0}^{t} S_{m}(t) h(s) \mathrm{d} s=\lim _{\varepsilon \rightarrow 0} \int_{\varepsilon}^{t} S_{m}(t-s) h(s) \mathrm{d} s=u(t)-S_{m}(t) u_{0}
$$

Thus,

$$
u(t)=S_{m}(t) u_{0}+\int_{0}^{t} S_{m}(t-s)\left(g+f_{0}(s, u(s))\right) \mathrm{d} s
$$

Step 4. Further regularity. From the smoothing effect of the semigroup $S_{m}(t)$ and the regularity observed above, we have that for any $\varepsilon>0, u(\varepsilon) \in H^{2 \alpha, q_{0}}(\Omega) \cap H_{0}^{1, q_{0}}(\Omega)$ for some $\alpha<1$ such that $2 \alpha-\frac{N}{q_{0}}>0$.

Therefore, for $t \geq \varepsilon, u(t)$ coincides with the unique solution in Theorems 2.1 and 2.2. In particular $u(t)$ is continuous in $\Omega$ and we can take $x \in \bar{\Omega}$ in (3.7).

Corollary 3.2 For $1 \leq q<\infty$ and $T>0$, we have that the solution $u$ in Theorem 3.1 satisfies, for $q \leq p \leq \infty$,

$$
\|u(t)\|_{L^{p}(\Omega)} \leq c(T)\left(1+t^{-\frac{N}{2}\left(\frac{1}{q}-\frac{1}{p}\right)}\left\|u_{0}\right\|_{L^{q}(\Omega)}\right) \quad 0<t \leq T .
$$

Proof. Following the argument in Step 2 in the proof of Theorem 3.1, we can bound the approximating sequence $u_{n}$ using the bound provided by the linear problem (3.5) to get

$$
\left\|u_{n}(t)\right\|_{L^{q}(\Omega)} \leq\left\|U^{n}(t)\right\|_{L^{q}(\Omega)} \leq c(T)\left(1+\left\|u_{0}\right\|_{L^{q}(\Omega)}\right), \quad 0 \leq t \leq T
$$

for all $n \geq 0$. Therefore, since $u \in C\left([0, T] ; L^{q}(\Omega)\right)$ is the limit of $u_{n}$ in $C\left([0, T] ; L^{q}(\Omega)\right)$ as $n \rightarrow \infty$, we have

$$
\|u(t)\|_{L^{q}(\Omega)} \leq c(T)\left(1+\left\|u_{0}\right\|_{L^{q}(\Omega)}\right), \quad 0 \leq t \leq T
$$

From (3.7) we also have that

$$
\|u(t)\|_{L^{\infty}(\Omega)} \leq c(T)\left(1+t^{-\frac{N}{2 q}}\left\|u_{0}\right\|_{L^{q}(\Omega)}\right), \quad 0<t \leq T
$$

Thus, by interpolation

$$
\|u(t)\|_{L^{p}(\Omega)} \leq\|u(t)\|_{L^{q}(\Omega)}^{\frac{q}{p}}\|u(t)\|_{L^{\infty}(\Omega)}^{1-\frac{q}{p}} \leq c(T)\left(1+t^{-\frac{N}{2}\left(\frac{1}{q}-\frac{1}{p}\right)}\left\|u_{0}\right\|_{L^{q}(\Omega)}\right), \quad 0<t \leq T .
$$

Let show now that the solutions of (1.1) in $L^{q}(\Omega)$ are unique for $1 \leq q<\infty$.
Theorem 3.3 Given $u_{0} \in L^{q}(\Omega), 1 \leq q<\infty$, there exists a unique function

$$
v \in C\left([0, \infty) ; L^{q}(\Omega)\right) \cap L_{\mathrm{loc}}^{\infty}\left((0, \infty) ; L^{\infty}(\Omega)\right), \quad v(0)=u_{0}
$$

that satisfies

$$
\begin{equation*}
v(t)=S_{m}(t) u_{0}+\int_{0}^{t} S_{m}(t-s)\left(g+f_{0}(\cdot, v(s))\right) d s, \quad t \geq 0 \tag{3.10}
\end{equation*}
$$

where $S_{m}$ denotes the semigroup generated by $\Delta+m(x) I$ with Dirichlet boundary conditions.

Therefore the function $u(\cdot)$ constructed in Theorem 3.1 is the unique function satisfying this.

Proof. Notice that the function $u$ constructed in Theorem 3.1 satisfies the assumptions above. So, let $v$ also satisfy the statement of the theorem. Then from (3.10) we have that, for any $\varepsilon>0$,

$$
v(t)=S_{m}(t-\varepsilon) v(\varepsilon)+\int_{\varepsilon}^{t} S_{m}(t-s)\left(g+f_{0}(\cdot, v(s))\right) \mathrm{d} s
$$

From the assumptions on $v$ we have that $h(s)=g+f_{0}(\cdot, v(s))$ satisfies, for any $T>0$, that $h \in L^{\infty}\left([\varepsilon, T] ; L^{q_{0}}(\Omega)\right)$. Then, the smoothing effect of the semigroup gives that

$$
v \in C\left([\varepsilon, T] ; H^{2 \gamma, q_{0}}(\Omega) \cap H_{0}^{1, q_{0}}(\Omega)\right), \text { for any } \gamma<1
$$

Hence, for $t \geq \varepsilon, v$ is a solution as in Theorem 2.1.
Hence, arguing as in (3.8) we have

$$
\sup _{\varepsilon \leq t \leq T}\|u(t)-v(t)\|_{L^{q}(\Omega)} \leq c(T)\|u(\varepsilon)-v(\varepsilon)\|_{L^{q}(\Omega)}
$$

with $c(T)$ not depending on $\varepsilon$.
The continuity of $u$ and $v$ at 0 in $L^{q}(\Omega)$, and the fact that $u(0)=v(0)$ imply $u=v$.

## 4 Final remarks and examples

(i) Note that Theorems 3.1 and 3.3 allow to define a strongly continuos nonlinear semigroup in $L^{q}(\Omega)$ as

$$
S(t) u_{0}=u\left(t ; u_{0}\right), \quad t \geq 0
$$

where $u\left(t ; u_{0}\right)$ is the solution in Theorem 3.1.
The asymptotic behavior of this semigroup is the same as the semigroup obtained for more regular initial data from Theorems 2.1] and 2.2. In fact, from (3.2) we get that for any $0<\varepsilon<T<\infty$ and for any bounded set of initial data $B \subset L^{q}(\Omega)$ we get that

$$
\{S(t) B, \varepsilon \leq t \leq T\} \quad \text { is bounded in } L^{\infty}(\Omega) .
$$

This implies, in turn that

$$
\left\{g+f_{0}\left(\cdot, u\left(t ; u_{0}\right)\right), \varepsilon \leq t \leq T, u_{0} \in B\right\} \quad \text { is bounded in } L^{q_{0}}(\Omega)
$$

and again the smoothing effect of the semigroup implies that

$$
\left.\{S(t) B, \varepsilon \leq t \leq T\} \quad \text { is bounded in } H^{2 \gamma, q_{0}}(\Omega) \cap H_{0}^{1, q_{0}}(\Omega)\right)
$$

for any $\gamma<1$.
(ii) Notice that the proofs in [2, [5] and [9] are based on energy estimates of the approximating solutions while the proof presented above is based on the maximum principle, in the form of the comparison principle. In particular, for the case of posing the problem in $L^{1}(\Omega)$, this avoid the use of Kato's inequality providing a unified argument. The equivalence between Kato's inequality and positive semigroups has been established in [1].
(iii) The standard theory for semilinear reaction-diffusion equations requires $f$ to satisfy some growth restriction in order to obtain a well-posed problem in $L^{q}(\Omega)$. Namely, the equation (1.1) is locally well posed provided $f$ satisfies

$$
\begin{equation*}
|f(x, t)-f(x, s)| \leq C\left(1+|s|^{p-1}+|s|^{p-1}\right)|t-s|, \quad t, s \in \mathbb{R} \tag{4.11}
\end{equation*}
$$

for all $x \in \Omega$, with

$$
p \leq p_{c}=1+\frac{2 q}{N} \quad\left(\text { i.e, for any } \quad q \geq q_{C}=\frac{N(p-1)}{2}\right)
$$

Notice that although the uniqueness in $L^{q}(\Omega)$, for $q>q_{\mathrm{C}}$, when $f$ satisfies the growth restriction (4.11), follows from with subcritical nonlinearities, the proof of Theorem 3.3 does not use any growth restriction on the nonlinear term (other than the fact of being almost-monotonic).
(iv) Theorems 3.1 and 3.3 extend to problems in unbounded domains in a natural way (see [2]). Also, the same techniques can be applied to obtain solutions in $\mathbb{R}^{N}$ in any $L_{U}^{q}(\Omega)$, locally uniform $L^{q}$ space, see [5] for a proof based on energy estimates. In the case of initial data in $L_{U}^{1}(\Omega), L$ in (1.4) was required to be bounded. By the techniques presented in here, no additional restriction is required on $L$ in order to obtain a solution.
(v) In [7], positive solutions of equation $u_{t}-\Delta u=-|u|^{p}$ with measures as initial data is considered. In particular, for positive $L^{1}$ densities, the solution is unique. We have shown that this uniqueness also holds for general $L^{1}$ initial data (with no assumption on their sign).
(vi) An example of nonlinearity for which all the previous results apply are the following:

$$
f_{0}(x, u)=\sum_{j=1}^{k} n_{j}(x) h_{j}(u)+f_{1}(x, u)
$$

with $h_{j} \in C^{1}(\mathbb{R}), h_{j}(0)=h_{j}^{\prime}(0)=0, j=1, \ldots, k$, and $f_{1}(x, s)$ is a Hölder continuous with respect to $x$ uniformly for $s$ in bounded sets of $\mathbb{R}, \partial_{s} f_{1}(x, s)$ is bounded in $x$ for $s$ in bounded sets of $\mathbb{R}$ and $f_{1}(x, 0)=\partial_{s} f_{1}(x, 0)=0, x \in \Omega$. This includes in particular the following cases, taking $f_{1} \equiv 0$ :

- Logistic equation

$$
f_{0}(x, u)=-n(x)|u|^{\rho-1} u
$$

with $n(x)$ a nonnegative $L^{r}(\Omega)$ function, not identically zero, and $\rho>1$. In this case, $L_{0}(x, R)=\rho R^{\rho-1} n(x)$ and we can always take $L \equiv 0$ in (1.4).

- Monotone polynomial nonlinearity

$$
f_{0}(x, u)=\sum_{j=2}^{k} n_{j}(x) u^{j}
$$

with $k$ odd and $n_{j} \in L^{d_{j}}(\Omega), d_{j}>N / 2,1 \leq j \leq k$ and $n_{k}(x) \leq a_{0}<0$ for all $x \in \Omega$. In this case, we can take

$$
L_{0}(x, R)=\sum_{j=2}^{k}(j-1) R^{j-1}\left|n_{j}(x)\right|
$$

and

$$
L(x)=k\left[\max _{u \in \mathbb{R}} \sum_{j=2}^{k} n_{j}(x) u^{j-1}\right]^{+}
$$

where $[g(x)]^{+}=\max \{g(x), 0\}$. Notice that $L, L_{0} \in L^{q_{0}}(\Omega)$ with $q_{0}=\min \left\{d_{1}, \ldots, d_{k}\right\}$.

- Polynomial nonlinearity with fractional powers

$$
f_{0}(x, u)=\sum_{j=1}^{k} n_{j}(x)|u|^{\rho_{j}-1} u
$$

with $1<\rho_{j}<\rho_{k}$ and $n_{j} \in L^{d_{j}}(\Omega), d_{j}>N / 2,1 \leq j \leq k$, and $n_{k}(x) \leq a_{0}<0$, $x \in \Omega$. We can take $L$ and $L_{0}$ analogous to the previous example.

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